



Universität  
Bremen

Cognitive  
Neuroinformatics

Faculty 03  
Mathematics/Computer Science

# Driving Simulator 2022

Serious Gaming for Autonomous Driving

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cognitive  
**neuroinformatics**

# Cognitive Neuroinformatics

## → Head of institute

→ Prof. Dr. Kerstin Schill

## → Project supervisors

→ Dr. Christoph Zetzsche

→ Dr. Joachim Clemens

→ Verena Schwarting

<http://www.cognitive-neuroinformatics.com>



Kerstin Schill



Christoph Zetzsche



Joachim Clemens



Verena Schwarting

# Research Systems

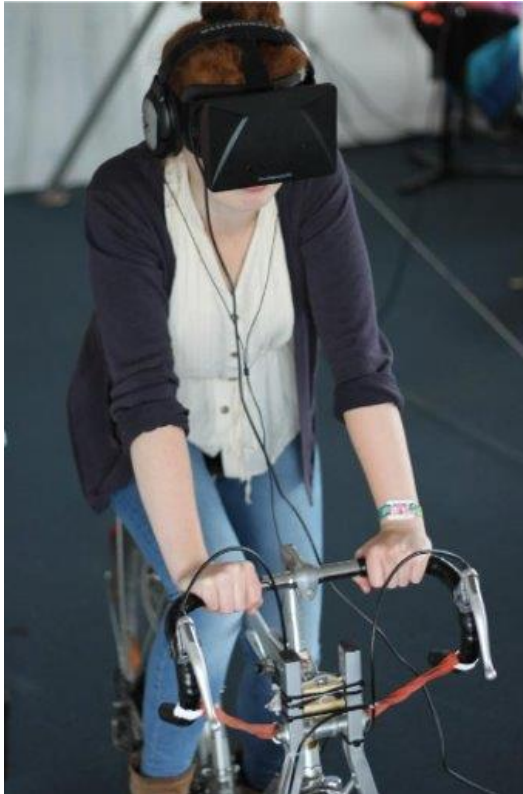
- Smart Hives
- Robohead
- Wheel-driven robots
- ADAS model cars
- EnEx-IceMole
- AO-Car Passat GTE



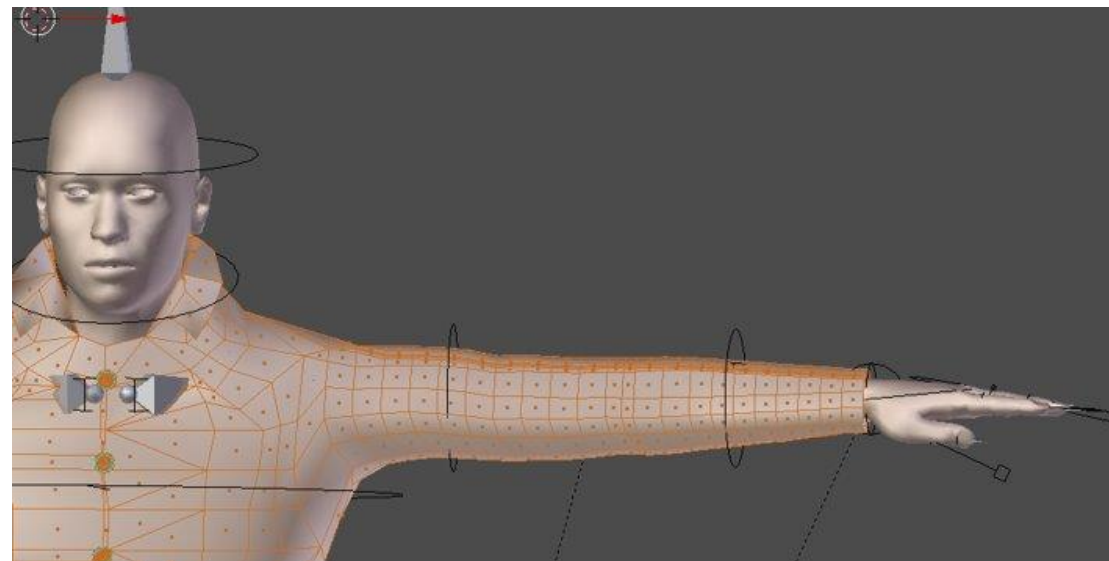
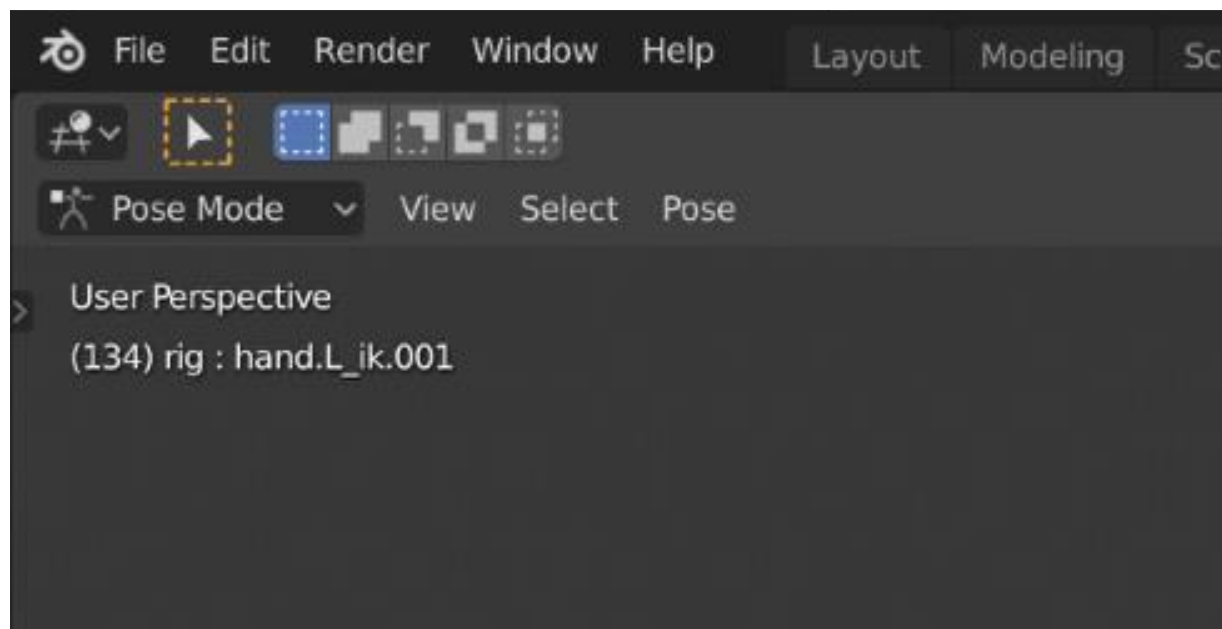
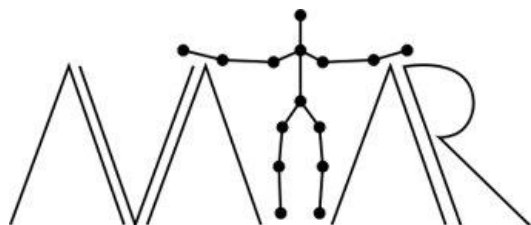


# Previous Projects

## Bicycle Simulator



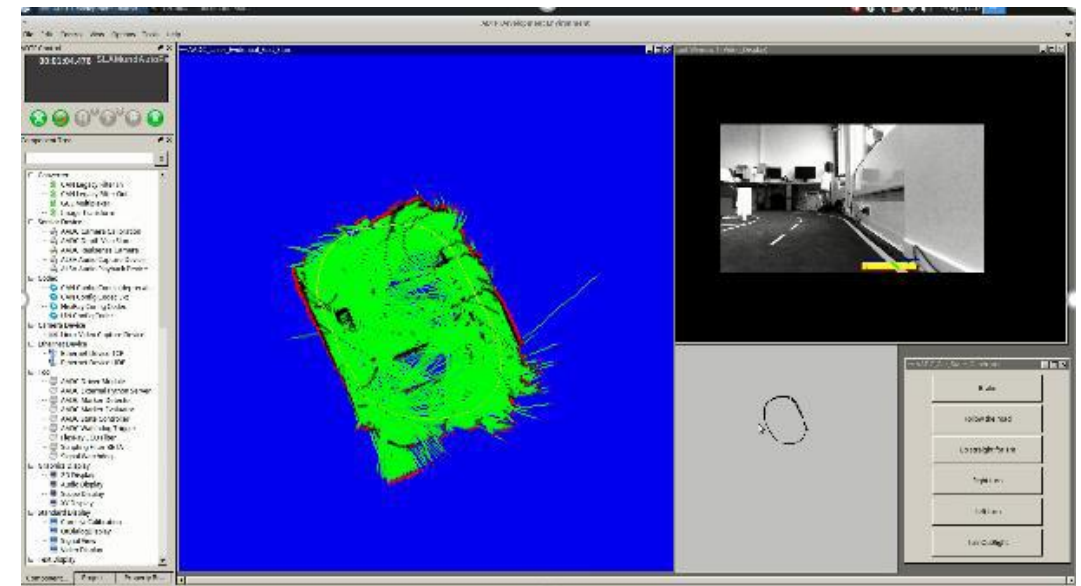
# Previous Projects





# Previous Projects

- Highly-automated driving
- Control of model vehicles
- Simulation environment
- 3 projects:
  - Build-up of test environment
  - Development of simulation environment
  - Cooperative maneuvers



# Driving Simulator 2021

→ Summer semester 2021

→ Basic modeling of Borgfeld

→ Street network, buildings, vegetation

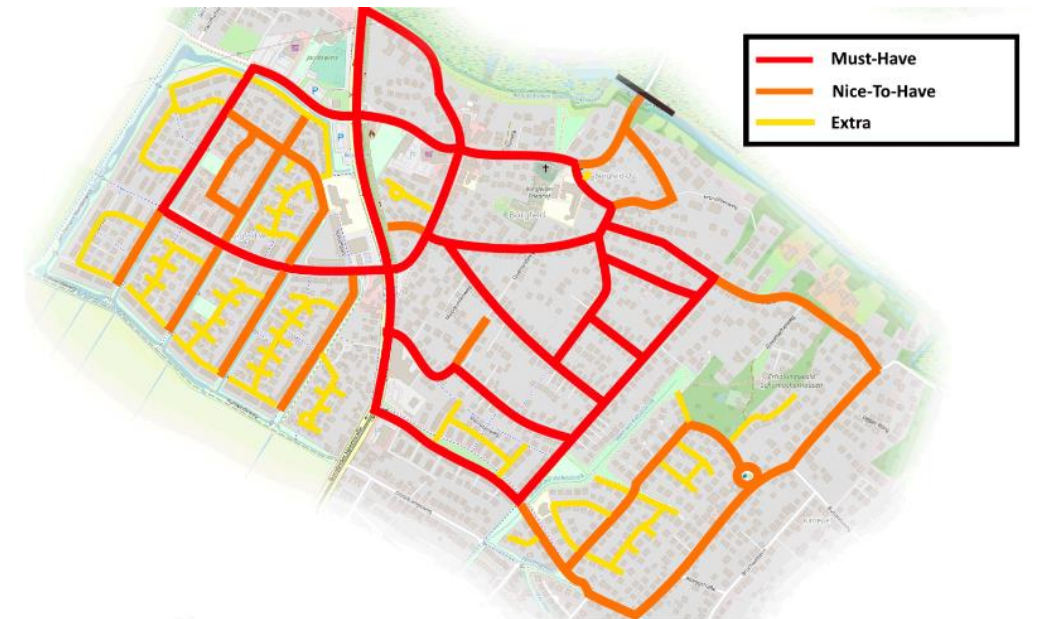
→ Scripting of traffic participants

→ Other vehicles, pedestrians, maybe bicycles

→ Interaction with simulation

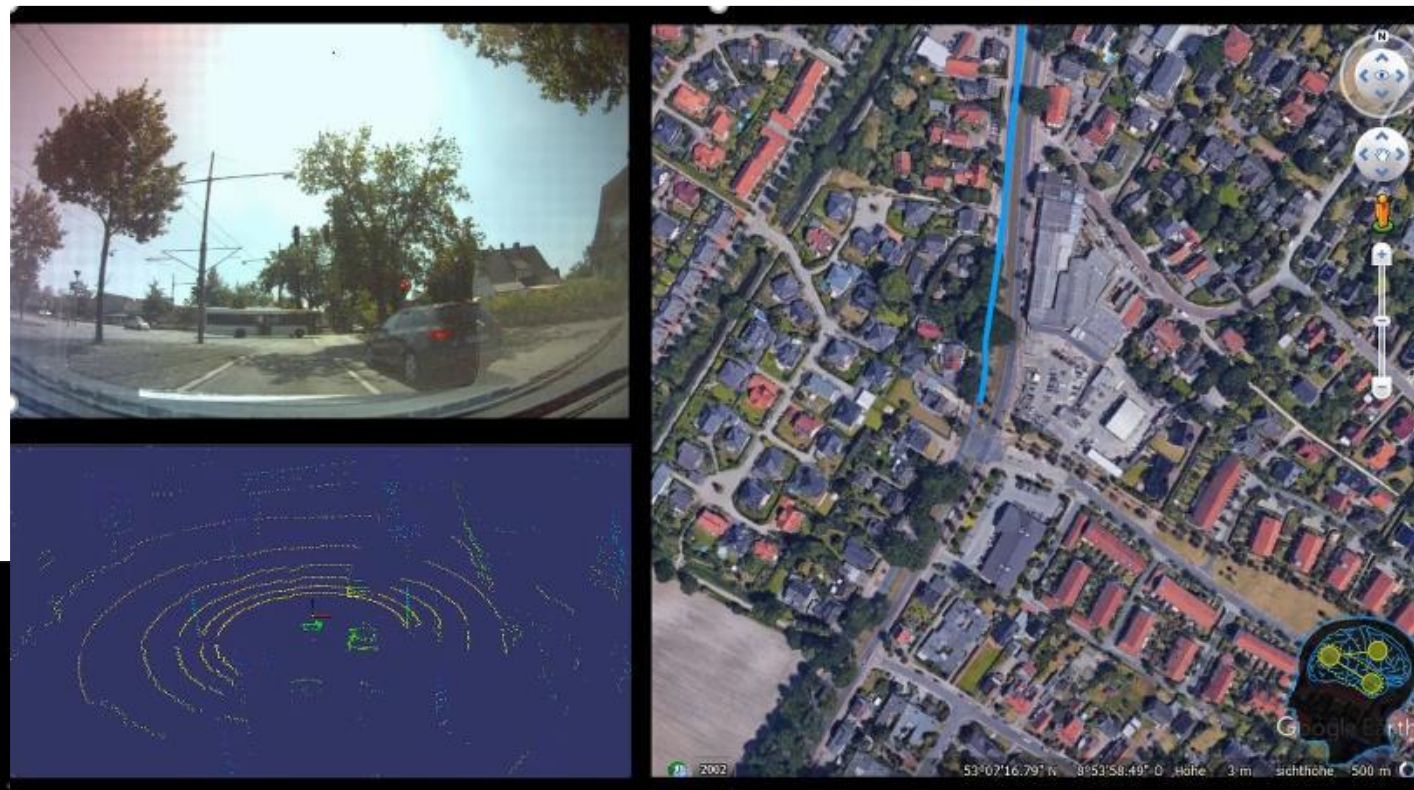
→ Manual control of traffic participants

→ Interface to autonomous algorithms





# BMWi/DLR Project OPA3L



Kartendaten: Google, GeoBasis-DE/BKG ©2009



# Simulation for Autonomous Driving

→ Open-source simulator: CARLA

→ Based on Unreal Engine

→ Vehicles, sensors, actuators, AI

→ Map editor: RoadRunner

→ Road network

→ Environment: traffic signs, buildings, vegetation, etc.



# Project Goals

- Continuation of Driving Simulator 2021
- Advanced Human Machine Interface (HMI)
- Driving in VR, walking, bicycling
- Interaction with AI vehicles
- Modelling of special events
  - Construction sites, emergency vehicles, accidents, etc.
- Extension of test environment
  - E.g. Uni-Campus
- Cooperative AI



Google, GeoBasis-DE/BKG ©2009



GeoBasis-DE / GeoInformationBremen ©2020



# Hardware and Software

## → Racing wheel and pedals

→ Logitech Driving Force

## → VR Headsets

→ Oculus Rift

→ HTC Vive

## → Simulation environment

→ CARLA (Unreal Engine)

## → Road network modeling

→ RoadRunner, OpenDrive

## → 3D Modelling

→ Program of choice



CARLA, Creative Commons Attribute

# Our Expectations

## → Self-organization

- Definition of overall goals and subgoals
- Resource management
- Organization of meetings and presentations

## → Interest in one or more of the following

- 3D modelling
- Basic scripting (e.g. Python)
- HMI
- AI algorithms

## → Preparation course: Advanced Problems of Multi-Sensory Cognition



# Contact



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